

Mutual Exclusion & Election

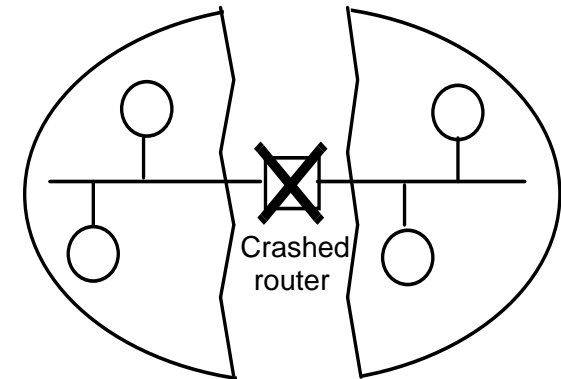
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Failure Assumptions

- Reliable channels
 - Guaranteed delivery **eventually** in asynchronous systems
 - Guaranteed delivery within bound D)
 - \Rightarrow network partitions/paths eventually repaired
- Independent processes $P_1 \dots P_n$

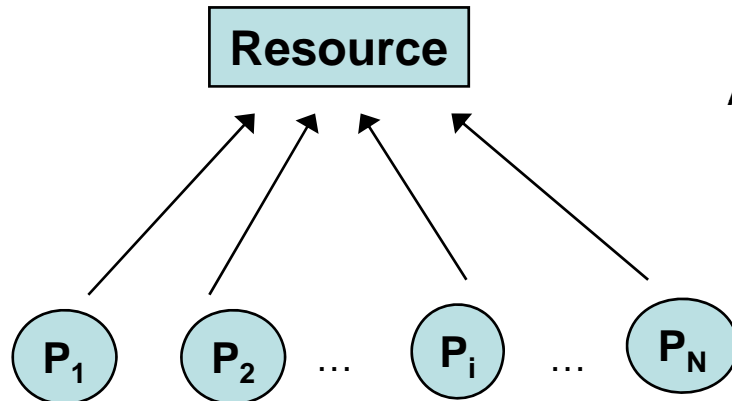
Network Partitioning



- Crash failures
 - **Cannot** be detected **reliably** in an asynchronous system by timeout
 - Heartbeats or probing in synchronous systems

Distributed mutual exclusion

- A number of processes want to access some shared resource
- Prevent interference, maintain consistency; critical section.



Application-level protocol:

```
enter()           // block till free
resourceAccess() // critical section
exit()            // free resource
```

General **requirements** for mutual exclusion

ME1: safety: at most one process may execute in the critical section at a time

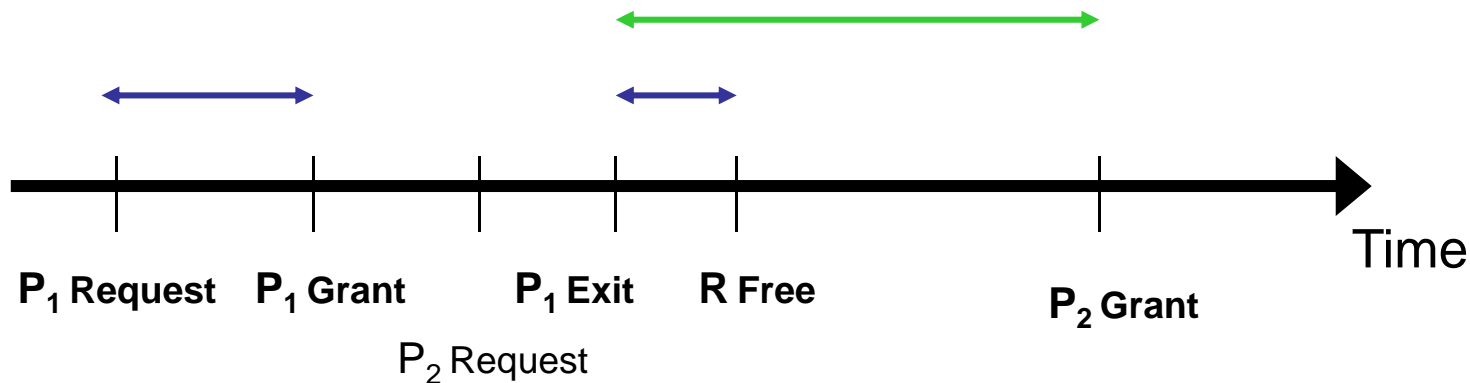
ME2: liveness: requests eventually succeed (*no deadlock, no starvation*)

ME3: ordering: if request A *happens-before* request B then grant A before grant B

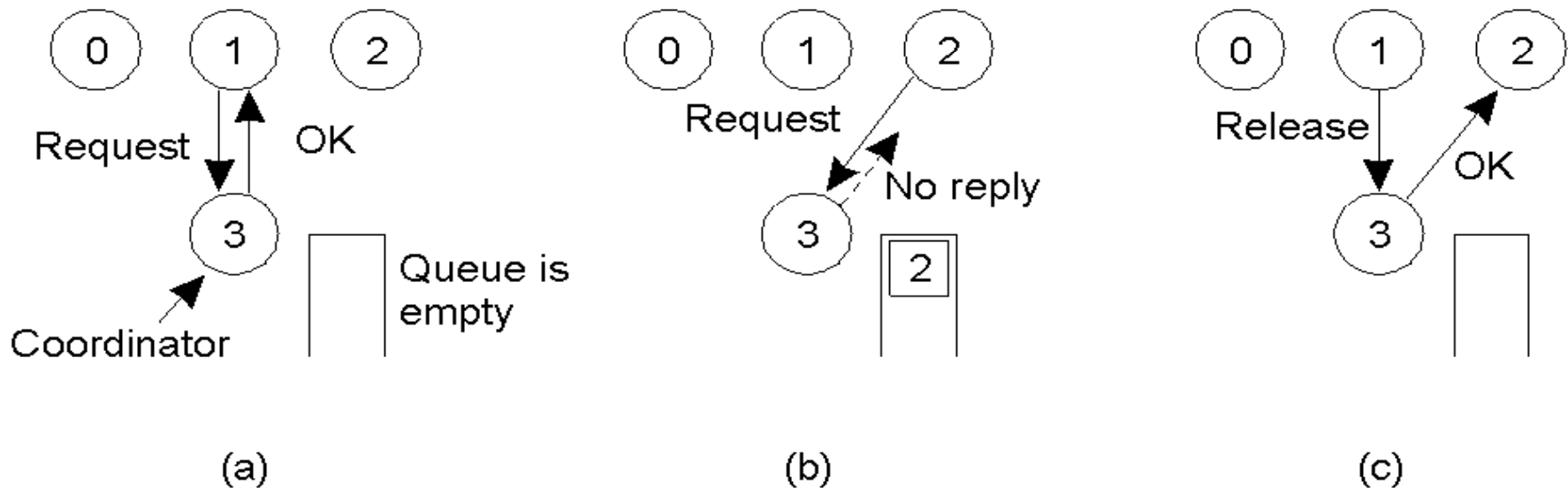
Problems: fault tolerance, performance

Performance Measures

- Bandwidth: number of messages required for entry and exit
- Client delay (entry and exit)
- Throughput (**Synchronization delay**)



Mutual Exclusion: A Centralized Algorithm



- Process 1 asks the coordinator for permission to enter a critical region. Permission is granted
- Process 2 then asks permission to enter the same critical region. The coordinator does not reply.
- When process 1 exits the critical region, it tells the coordinator, which then replies to 2

Mutual Exclusion: A Centralized Algorithm

- **Shortcomings**

- The coordinator is a single point of failure, so if it crashes, the entire system may go down.
 - Wait; why not just elect another coordinator?
 - You can. The only concern is figuring out who has access to the critical section (state: current owner, queue).
 - How do you tell the difference between a dead coordinator and “permission denied”?
- In a large system a single coordinator may become a performance bottleneck.

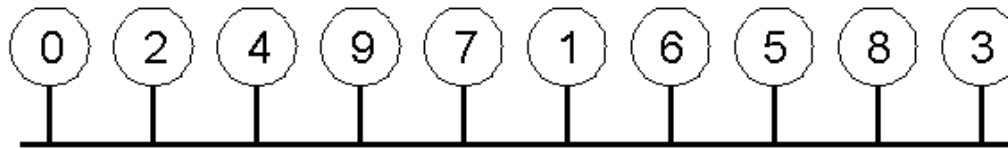
- **Advantages:**

- Simple
- Reasonable efficient

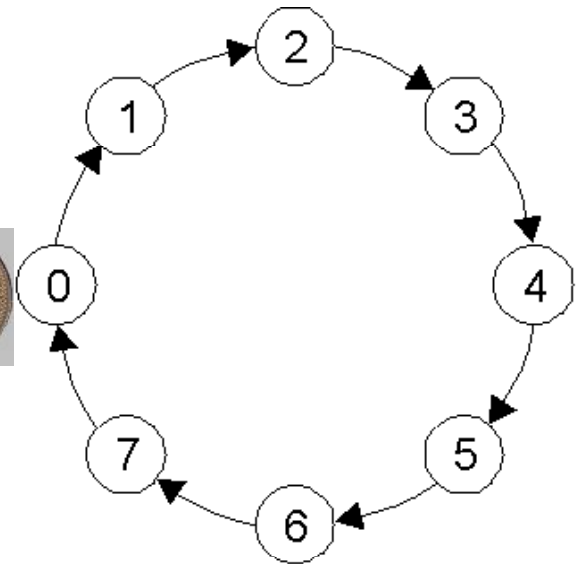
Mutual Exclusion: A Centralized Algorithm

- Bandwidth
 - 3 messages to enter and leave a critical region: A request, a grant to enter and a release to exit
- Client Delay:
 - Entry: 2 messages: request + grant
 - Exit: 0 (asynchronous sending of release)
- Synchronization Delay: release + grant

A Token Ring Algorithm



(a)



(b)

- An unordered group of processes on a network.
- A logical ring constructed in software.
- Token holder may enter CS

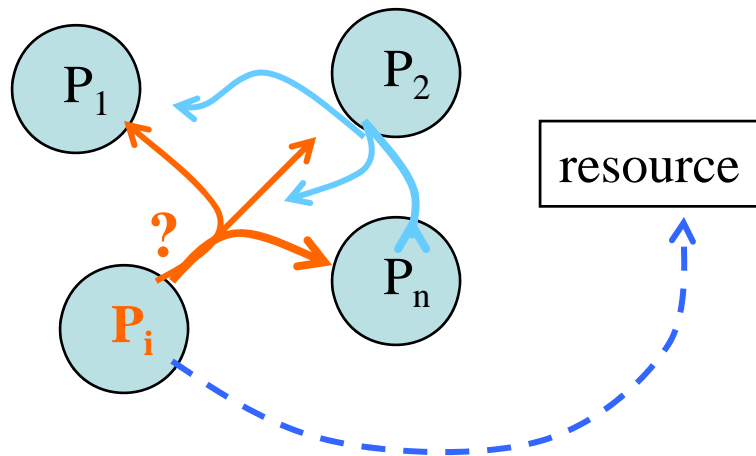
Token Ring

- Client Delay
 - Entry: Wait: $0 \dots N$ hops ($N/2$ in average)
 - Exit: send 1 msg (asynchronously)
- Synchronization Delay
 - $0 \dots N$ hops ($N/2$ in average)
- Bandwidth
 - Always uses bandwidth to circulate token, used or not.

Ricart and Agrawala's Algorithm [81]

- Fully Distributed
- Optimized version of Lamports '78 algorithm
- Send “request” to $N-1$ other processes.
- Execute CS when “reply OK” permission is received from all other processes.
- P_i maintains Lamport Clock
 - I.e., adjust counter C_i on every internal event, and send and receive
- Break ties with Lamport time-stamp.

Ricart and Agrawala



- The general idea:
 - ask everybody
 - wait for permission from everybody

The problem:

- several simultaneous requests (e.g., P_i and P_j)
- all members have to agree (*everybody*: “first P_i then P_j ”)

Ricart – Agrawal's Algorithm

On initialization

state := RELEASED;

To enter the section

state := WANTED;

T := request's timestamp;

Multicast *request* to all processes;

Wait until (number of replies received = $(N-1)$);

state := HELD;

} request processing deferred here

On receipt of a request $\langle T_i, p_i \rangle$ at p_j ($i \neq j$)

if (*state* = HELD or (*state* = WANTED and $(T, p_j) < (T_i, p_i)$))

then

 queue *request* from p_i without replying;

else

 reply OK immediately to p_i ;

end if;

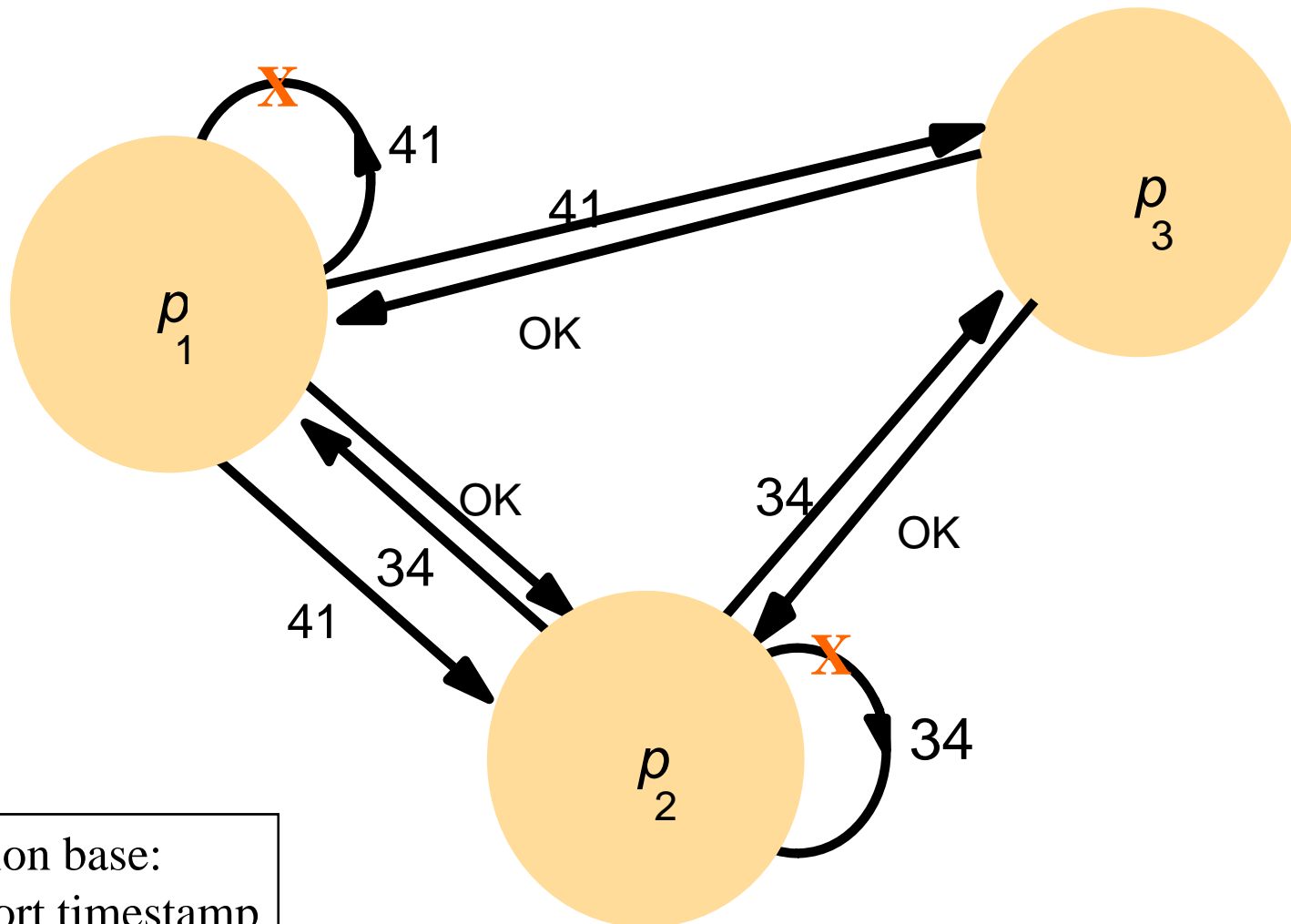
To exit the critical section

state := RELEASED;

reply OK to all queued requests;

Ricart – Agrawala EX.

P1 and P2 requests access concurrently at time 41 and 34



Decision base:
Lamport timestamp

X: $i < j$

Performance

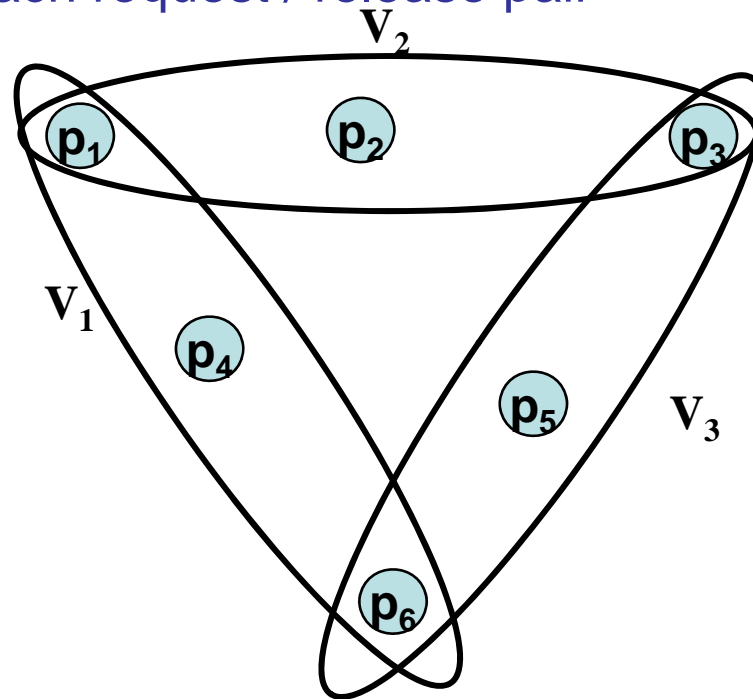
- Gaining entry: $2(n-1)$ messages per request without HW-multicast
 - $N-1$ to multicast request
 - $N-1$ replies
- Client Entry Delay: 1 round-trip time (multicasting is counted as 1 step)
- Client Exit Delay: 1 message multicast round to $0..n-1$ queued processes
- Synchronization delay is one message
- **N -points of failure**

Maekawa's Algorithm [1981]

- **Idea:** Get permission from only a subset of processes.
 - **quorum:**
 - "The minimal number of officers and members of a committee or organization, usually a majority, who must be present for valid transaction of business."

Voting

- To enter its CS, a process gets permission from all members of its group
 - A process may grant permission to only one process at a time (between each request / release pair)



- Complexity depends on group size
 - Want to minimize group size

Voting-Sets

Voting-set V_i for P_i

1. $\forall i, j: V_i \cap V_j \neq \emptyset$
 - Safety: at least one common member of any two voting-sets
 2. V_i contains process p_i
 - Saves a message
 3. $|V_1| = |V_2| = \dots = |V_N| = K$
 - *Fairness: every process has a voting set of the same size*
 4. Each process is in M of the voting sets V_i 's
 - Each processor has the same responsibility
- Minimal K satisfying 1..4 is $c\sqrt{N}$.
 - Heuristic algorithms exist

Maekawa's algorithm – part 1

On initialization

state := RELEASED;

voted := FALSE;

For p_i to enter the critical section

state := WANTED;

Multicast *request* to all processes in $V_i - \{p_i\}$;

Wait until (number of replies received = $(|V_i| - 1)$);

state := HELD;

On receipt of a request from p_i at p_j ($i \neq j$)

if (*state* = HELD or *voted* = TRUE)

then

 queue *request* from p_i without replying;

else

 send *reply* to p_i ;

voted := TRUE;

end if

Maekawa's algorithm – part 2

For p_i to exit the critical section

state := RELEASED;

Multicast release to all processes in $V_i - \{p_i\}$;

On receipt of a release from p_i at p_j ($i \neq j$)

if (queue of requests is non-empty)

then

remove head of queue – from p_k , say;

send reply to p_k ;

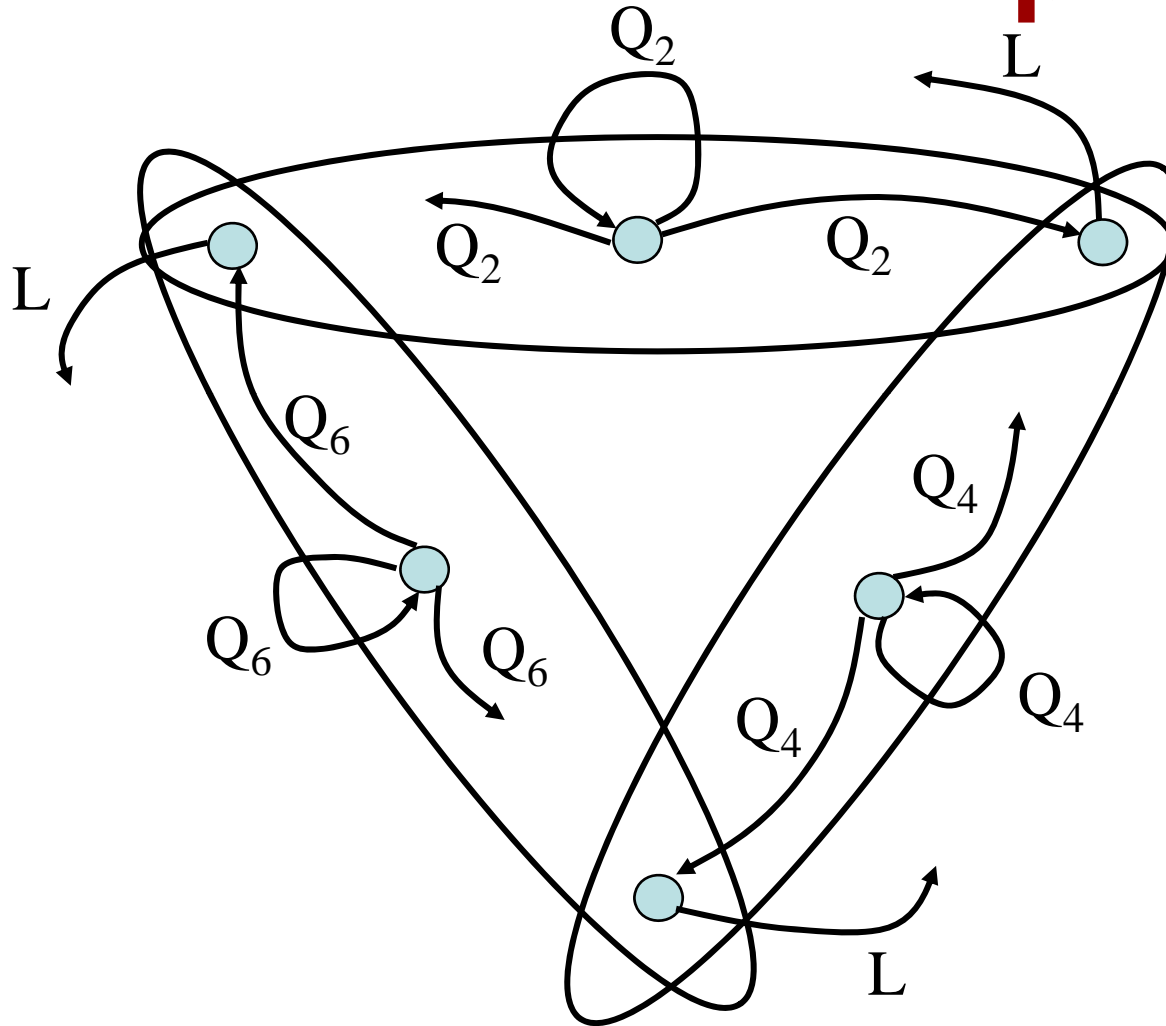
voted := TRUE;

else

voted := FALSE;

end if

Deadlock Example



Concurrent request \Rightarrow common processes votes to left most quorum \Rightarrow
Circular wait possible \Rightarrow deadlock possible

Comparison

Algorithm	Messages per entry/exit	Synchronization Delay (seq. msgs)	Problems
Centralized	3	2	Coordinator crash Client crash in cs
Token ring	1 ... ∞	0..n-1 (Avg: n/2)	Lost token, process crash
Ricart & Agrawali	2 (n - 1)	1	Crash of any process
Maekava voting	$3\sqrt{N}$	2	Crash of process in voting set

A comparison of mutual exclusion algorithms.

Notice: the system may contain a remarkable amount of sharable resources!

Summary

- All distributed algorithms suffer badly in event of crashes.
- Special measures and additional complexity must be introduced to avoid having a crash bring down the entire system.

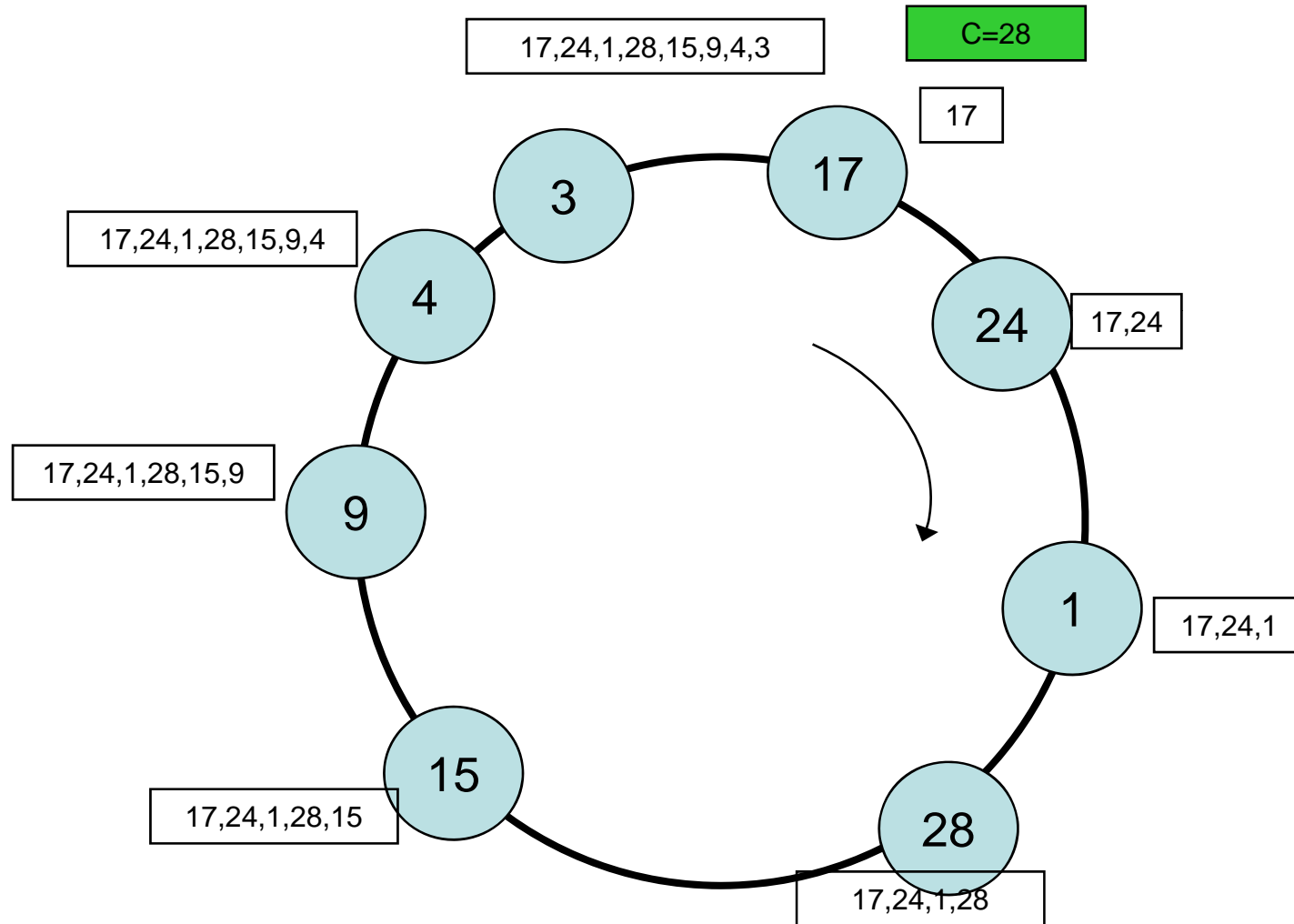
Election Algorithms

- Need:
 - algorithms based on the activity of a special role (coordinator, initiator)
 - election of a coordinator: initially or after some special event (e.g., the previous coordinator has disappeared)
- Premises:
 - each member of the group
 - knows the identities of all other members
 - does not know who is up and who is down
 - all electors use the same algorithm
 - election rule: the member with the highest process id

Election Requirements

- **E1:** (*safety*) A participant process p_i has either $electd_i = \perp$, or $electd_i = p$, where p is the *non-crashed* process having the largest process identifier
- **E2:** (*liveness*) All processes p_i participate and will at some point in time set their $electd_i$ variable to a value different from ? or crash
- $\perp =$ undefined

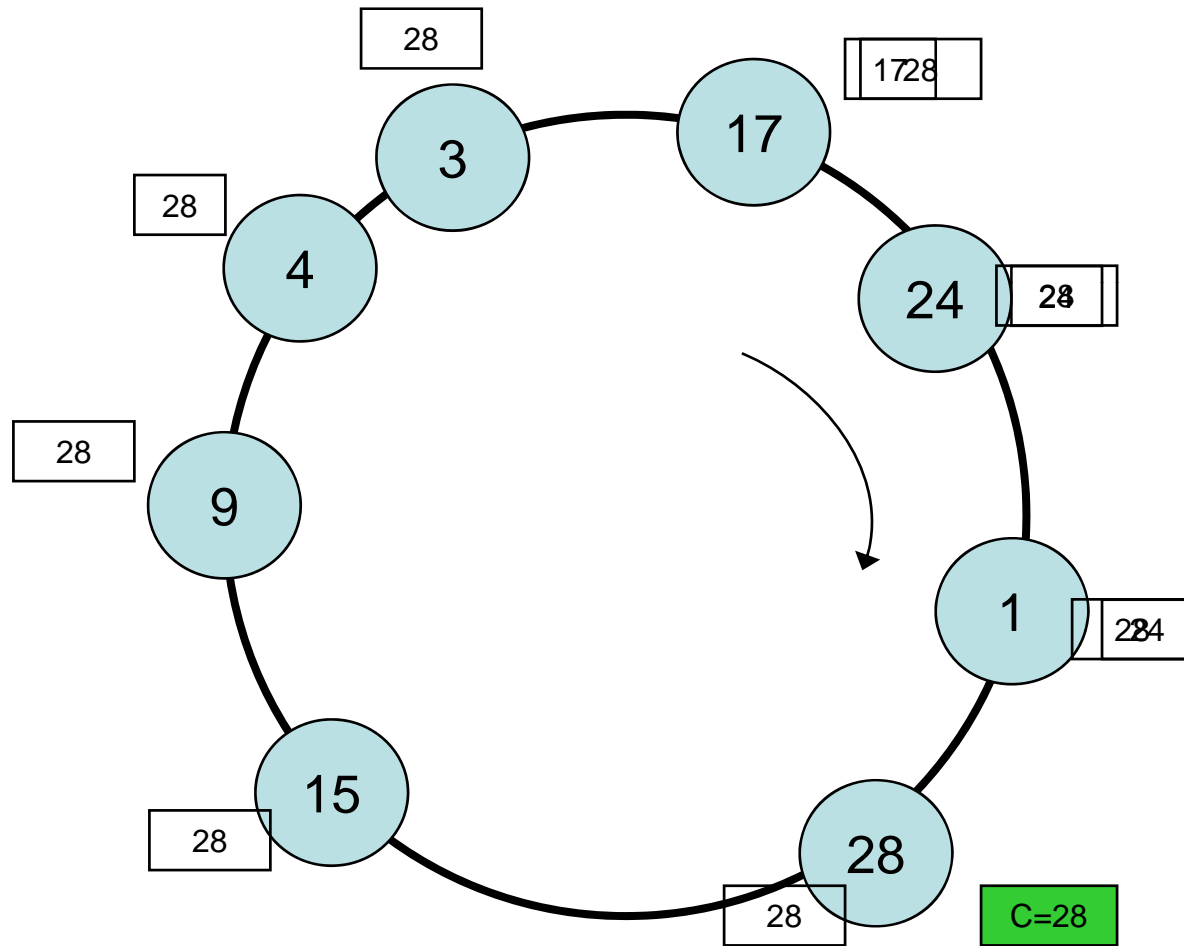
A ring-based election 1



Chang-Roberts

- Improvement Idea:
 - When a node receives a token with smaller id than itself, why should it keep forwarding it?
 - It is a waste, we know that that id will never win!
 - Lets drop tokens with smaller ids than ourselves!
 - Mark nodes that has already participated in an ongoing election to kill concurrent elections
 - A process declares itself elected when it receives its own ID back

Chang-Roberts



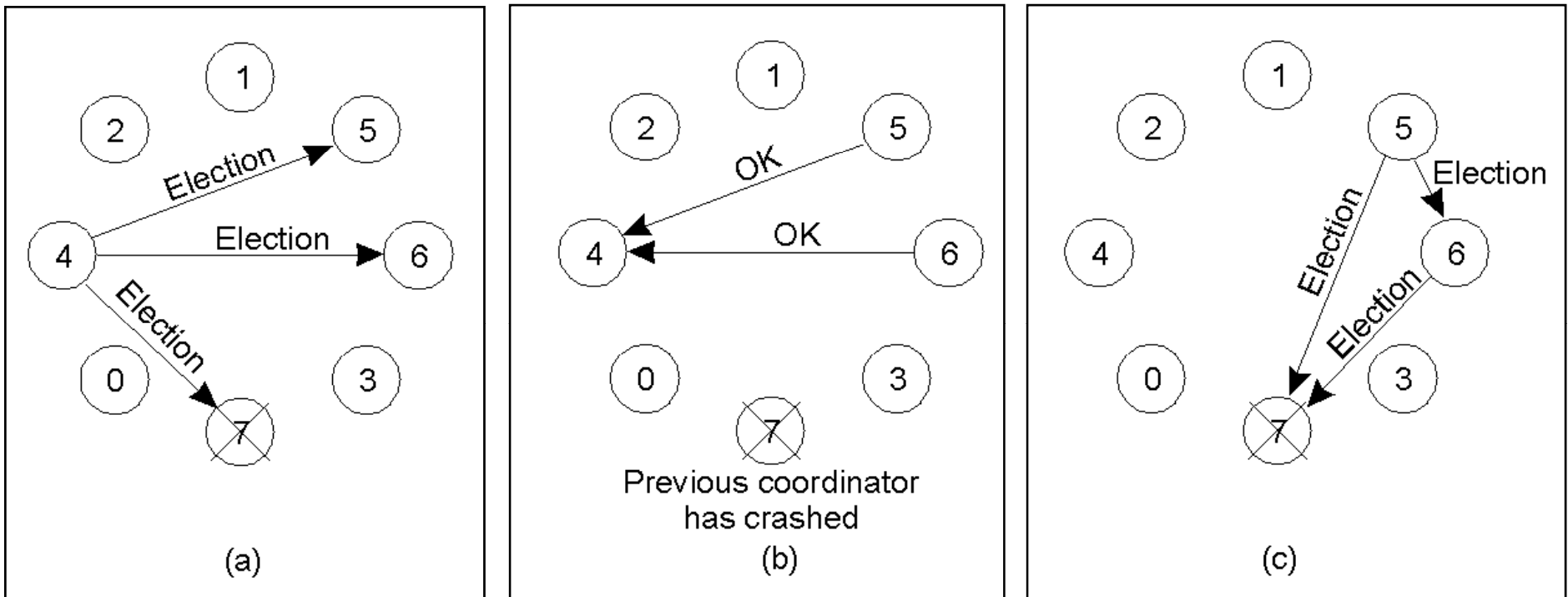
Performance

- Bandwidth: $3N-1$
 - $N-1$ in worst case to reach process with highest ID +
 - One round of N messages before node with highest ID can announce it is a winner +
 - One round of N messages to inform other nodes about coordinator
- Turnaround: an election takes sequential 3 rounds

Bully Algorithm

- Bully
 - *A person who is habitually cruel, especially to smaller or weaker people*
- Processes may fail during election
- Uses timeout to detect failure (\Rightarrow assumes synchronous system)
- Each process knows processes with higher ID's
- 3 message types
 - A process sends *Election* to all processes with larger IDs to start an election
 - *Answer (OK)*: to election message tells receiver that sender is alive and that receiver must shut-up
 - *Coordinator*: inform about new coordinator

The Bully Algorithm (2)



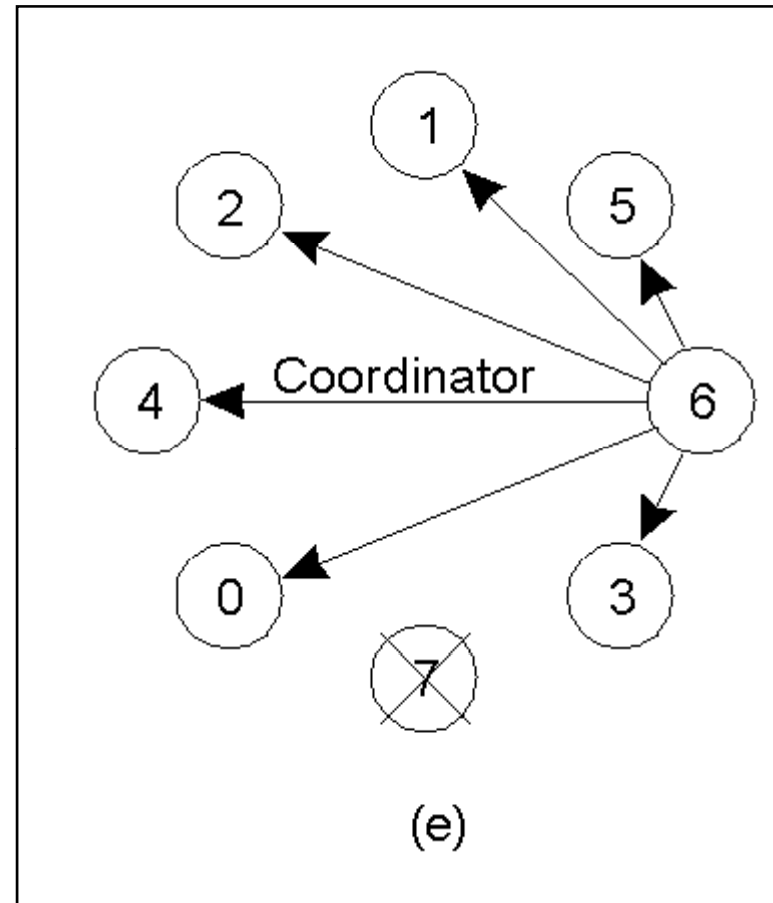
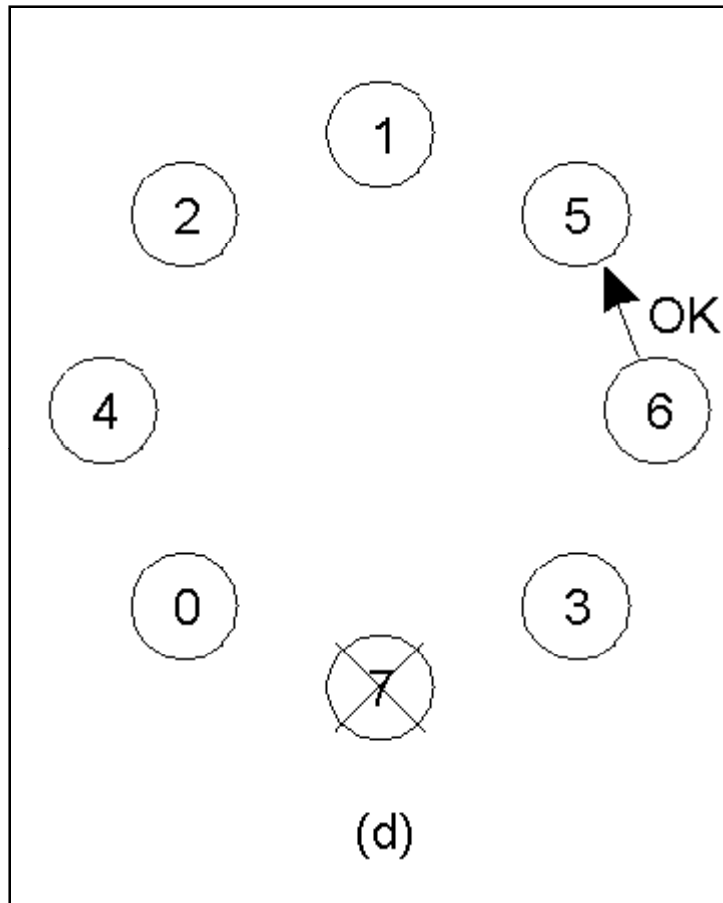
Coordinator id 7 is dead

(a) Process 4 holds an election

(b) Process 5 and 6 respond, telling 4 to stop

(c) Now 5 and 6 each hold an election

The Bully Algorithm (3)

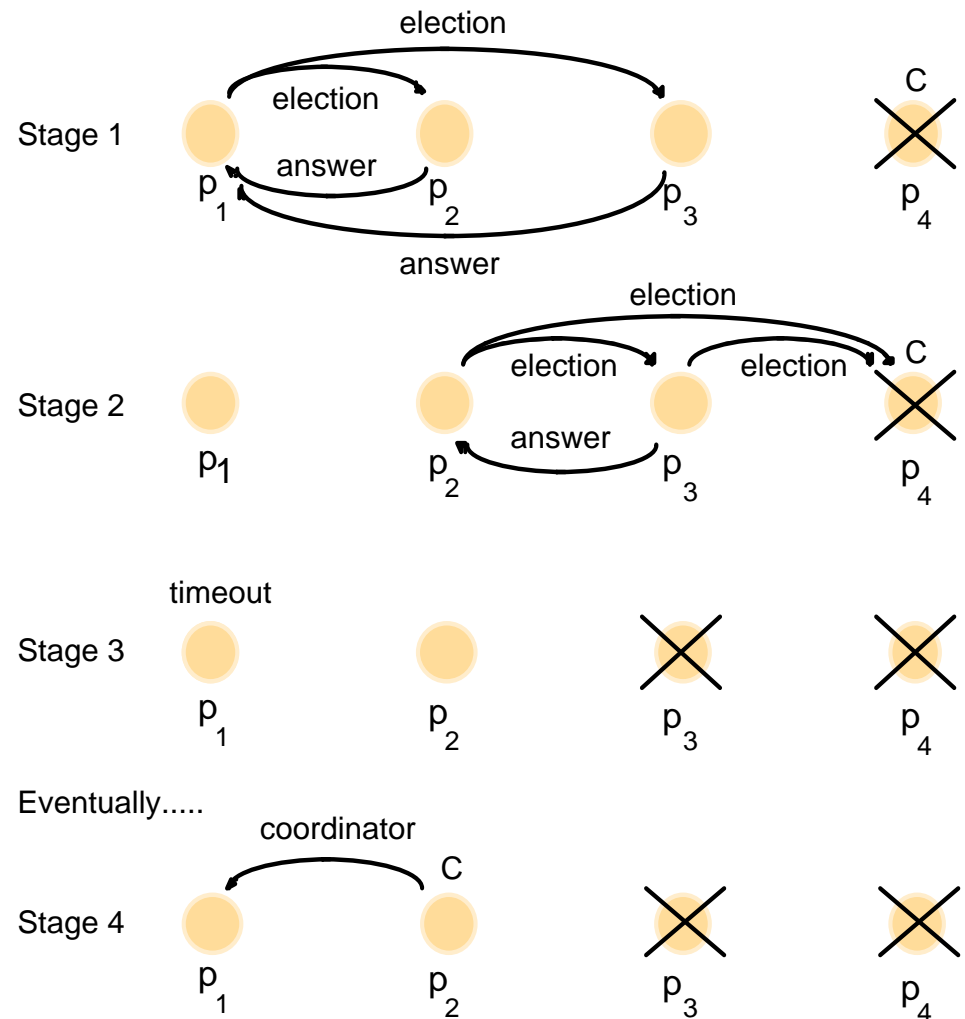


(d) Process 6 tells 5 to stop

(e) Process 6 wins and tells everyone

The bully algorithm

- P_1 detects crash of coordinator p_4
- P_1 decides to hold an election
- P_2 and p_3 tells P_1 to shut up and hold their own (concurrent) elections
- p_3 tells P_2 to shut up
- p_3 times out waiting from answer from P_4 and declares itself the coordinator
- Alas, P_3 fails
- P_1 times out waiting for coordinator and decides to hold an election
- P_2 starts an election and realizes that it is largest living process and declares itself the coordinator p_2 ,



END